



Learning in Repeated Games

Game Theory Course: Jackson, Leyton-Brown & Shoham



- We will cover two types of learning in repeated games.
 - Fictitious Play
 - No-regret Learning
- In general Learning in Game Theory is a rich subject with many facets we will not be covering.



- Initially proposed as a method for computing Nash equilibrium.
- Each player maintains explicit belief about the other players.
 - Initialize beliefs about the opponent's strategies.
 - Each turn:
 - Play a best response to the assessed strategy of the opponent.
 - Observe the opponent's actual play and update beliefs accordingly.

Formally

- Maintain counts of opponents actions
 - For every $a \in A$ let w(a) be the number of times the opponent has player action a.
 - Can be initialized to non-zero starting values.
- Assess opponent's strategy using these counts:

$$\sigma(a) = \frac{w(a)}{\sum_{a' \in A} w(a')}$$

- (pure strategy) best respond to this assessed strategy.
 - Break ties somehow.



Example using matching pennies



Round	l's action	2's action	l's beliefs	2's beliefs
0			(1.5,2)	(2,1.5)
I	Т	Т	(1.5,3)	(2,2.5)
2	Т	н	(2.5,3)	(2,3.5)
3	Т	н	(3.5,3)	(2,4.5)
4	н	н	(4.5,3)	(3,4.5)
5	н	н	(5.5,3)	(4,4.5)
6	н	н	(6.5,3)	(5,4.5)
7	н	Т	(6.5,4)	(6,4.5)
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Convergence

Theorem

If the empirical distribution of each player's strategies converges in fictitious play, then it converges to a Nash equilibrium.



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Theorem

Each of the following are a sufficient conditions for the empirical frequencies of play to converge in fictitious play:

- The game is zero sum;
- The game is solvable by iterated elimination of strictly dominated strategies;
- The game is a potential game;
- The game is $2 \times n$ and has generic payoffs.



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Definition (Regret)

The regret an agent experiences at time t for not having played s is $R^t(s) = \max(\alpha^t(s) - \alpha^t, 0).$

Definitions



Definition (Regret)

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Definition (No-regret learning rule)

A learning rule exhibits no regret if for any pure strategy of the agent s it holds that $Pr([\liminf R^t(s)] \le 0) = 1$.





• Example learning rule that exhibits no regret: Regret Matching.

$\sigma_i^{t+1}(s) = \frac{R^t(s)}{\sum_{s' \in S} R^t(s')},$

No-regret Learning

Regret Matching

where $\sigma_i^{t+1}(s)$ is the probability that agent *i* plays pure strategy s at time t + 1.



• At each time step each action is chosen with probability proportional to its regret. That is,



No-regret Learning Regret Matching

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where $\sigma_i^{t+1}(s)$ is the probability that agent i plays pure strategy s at time t + 1.

• Converges to a correlated equilibrium for finite games.



